Introduction to Hardware and Closed-loop System

Prof. Jamie Paik

Dr. Yuhao Jiang Reconfigurable Robotics Laboratory EPFL, Switzerland









Introduction to Hardware

- Hardware list
 - Already Provided
 - Microcontroller: ESP32
 - Support Arduino ecosystem;
 - Bluetooth + WIFI communication;
 - Duo-core CPU;
 - Servo: 5V DC motor servo x 2
 - Read position;
 - Move using position/velocity commands;
 - Power supply
 - 5V USB power supply
 - Battery optional
 - To be selected
 - Sensors: at least 1 kind









• **Closed loop System:** A system/device that can read its current state, and automatically process and regulate to maintain a desired state.

Essential hardware:

- Sensors: reading states
- Controllers: computing and processing
- Actuators: regulating states

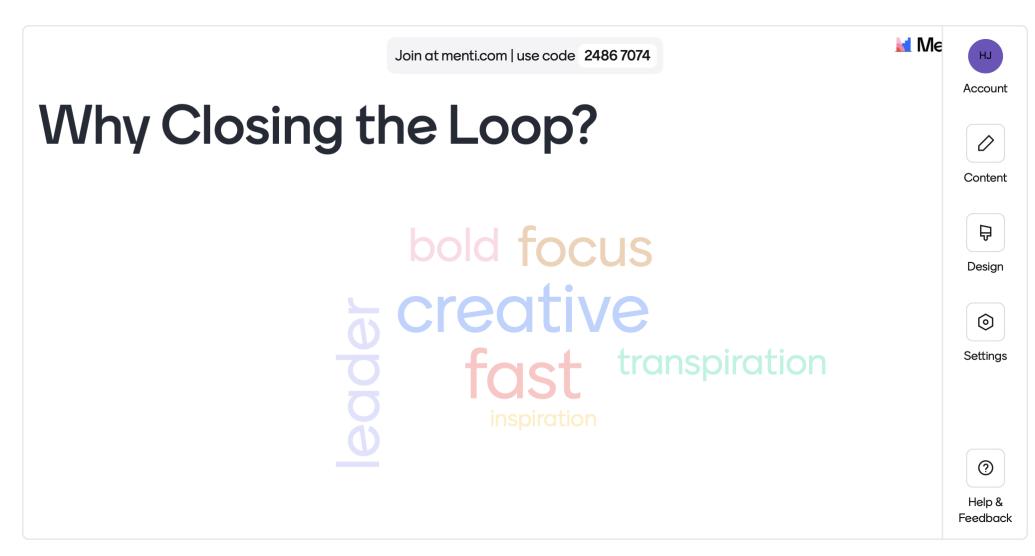
Join at menti.com | use code 2486 7074







Why Closing the Loop?







Why Closing the Loop?

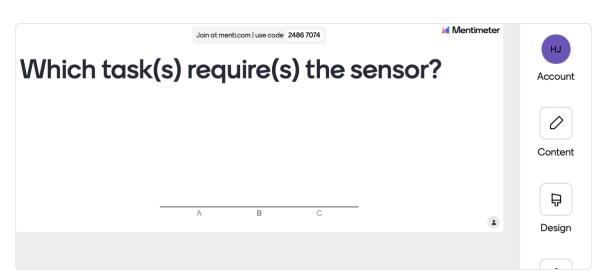
- Automatic and Sustainable
 - Reducing human intervention: accomplishing pre-set task automatically;
 - **Efficiency optimization**: advance control methods permit optimizations on energy usage and working conditions;
- Robust and Adaptable
 - Disturbance Rejection;
 - Environment Adaptation: automatically adjust to adapt environment changes and internal system malfunctions;
- Accurate and Rapid Response
 - Reducing errors: estimate error in real time and regulate;
- Safe
 - Fail-Safe Operations: force, speed limits;

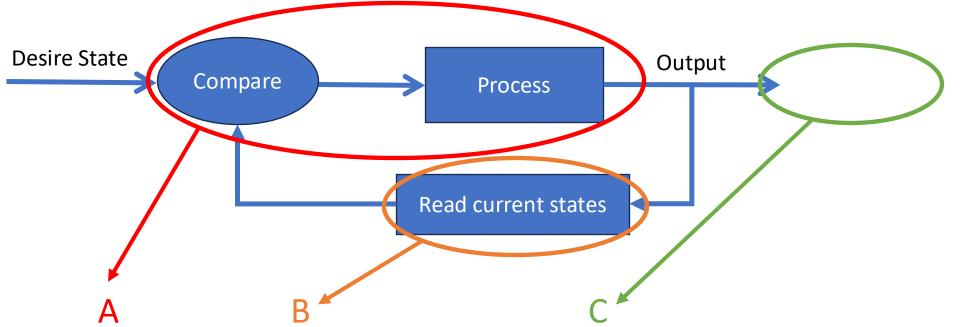




Essential hardware:

- **Sensors**: reading states
- Controllers: computing and processing
- Actuators: taking command from controller, regulating states









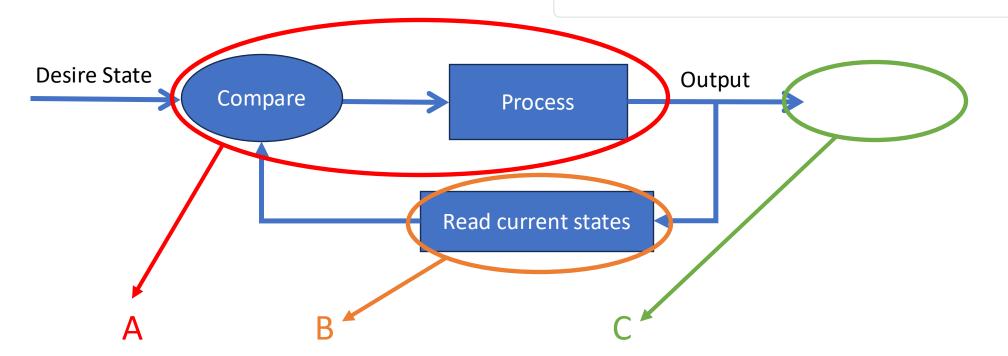
Essential hardware:

- **Sensors**: reading states
- Controllers: computing and processing
- Actuators: taking command from controller, regulating states

Which task(s) require(s) the controller?

Join at menti.com | use code 2486 7074



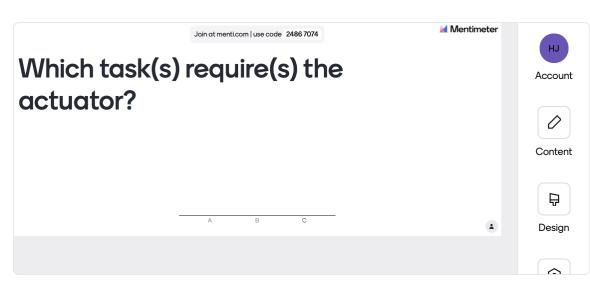


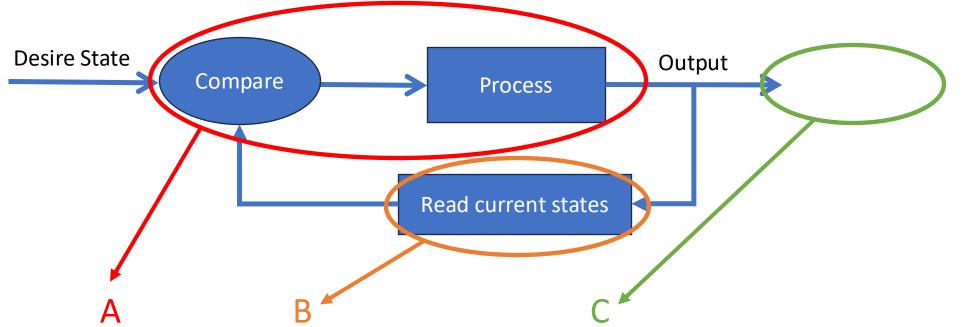




Essential hardware:

- **Sensors**: reading states
- Controllers: computing and processing
- Actuators: taking command from controller, regulating states









Autonomous Car



Closed-loop Systems

Autonomous Factory



Smart Home



Biology





RRL

Goal

- Autonomous cruising
 - Maintain speed
 - Stay in the lane
 - Avoid collision

Controllable Objects

- Engine / Motor throttle
- Steering
- Brake

Information

- Current location
- Map
- Speed
- Power state
- Road situation
- Traffic Info

Control Input

- Goal speed
- Goal heading

Control Output

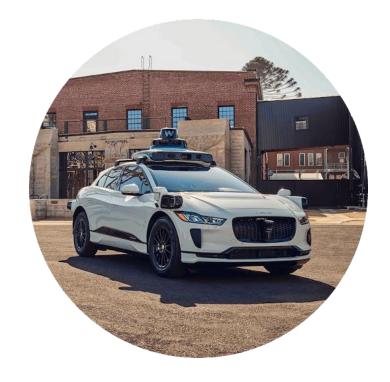
- Power output
- Steering angle
- Brake

Cost Factors

- Fuel efficiency
- Time
- Comfort
- Safety

Control Feedback State

- True speed
- True heading







Goal

- Maintain room temperature and humidity
 - Save energy
 - Comfortable, healthy
 - Economic

Controllable Objects

- AC system
 - Air flow rate
 - Air temperature
- Window, door
- Window shades

Information

- Outdoor climate
- Outdoor air condition
- Indoor air condition
- AC system state
- Electricity price
- Indoor people activity

Control Input

Goal room temperature and humidity

Control Output

- AC air flow rate
- AC air temperature
- Window, door
- Window shades

Control Feedback State

True room temperature and humidity

Cost Factor

- Economy
- Comfort
- Healthy







Goal

- Blood glucose regulation in human body
 - Maintain blood glucose level

Controllable Objects

- Pancreas
 - Insulin secretion
 - Reduce blood sugar
 - Glucagon secretion
 - Signal the liver to produce glucose
- Brain
 - Eat!
 - No more food!

Information

- Pancreatic Beta Cell
 - Glucose sensors
- Diet condition

Control Input

Normal/healthy blood glucose level

Control Output

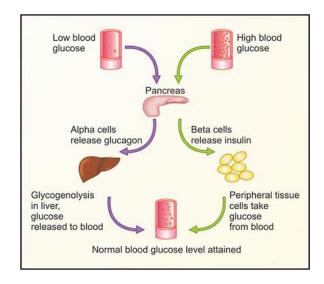
- Secretion speed of Insulin
- Secretion speed of Glucagon

Control Feedback State

True blood glucose level

Cost Factor

Diet condition







Goal

- Anti-Lock Braking System (ABS) in vehicles
 - Prevent lock-up during braking
 - Maintain high braking power and traction

Controllable Objects

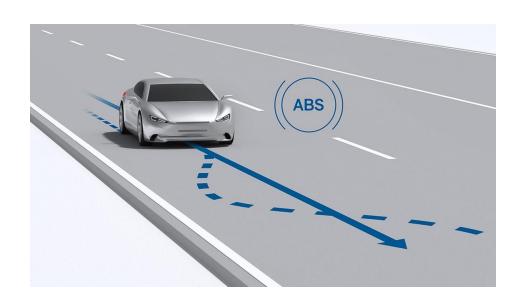
Brake hydraulic pump

Information

- Wheel speed
- Brake hydraulic pump pressure

Cost Factor

- Passenger comfort
- Braking distance







Goal

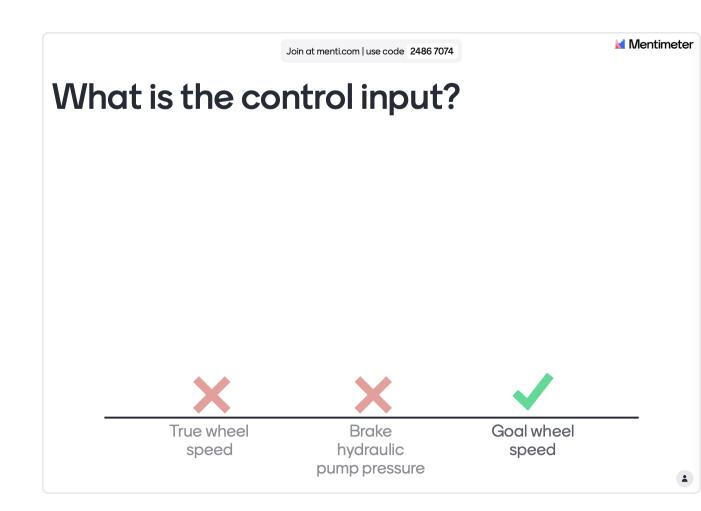
- Anti-Lock Braking System (ABS) in vehicles
 - Prevent lock-up during braking
 - Maintain high braking power and traction

Controllable Objects

Brake hydraulic pump

Information

- Wheel speed
- Brake hydraulic pump pressure







Goal

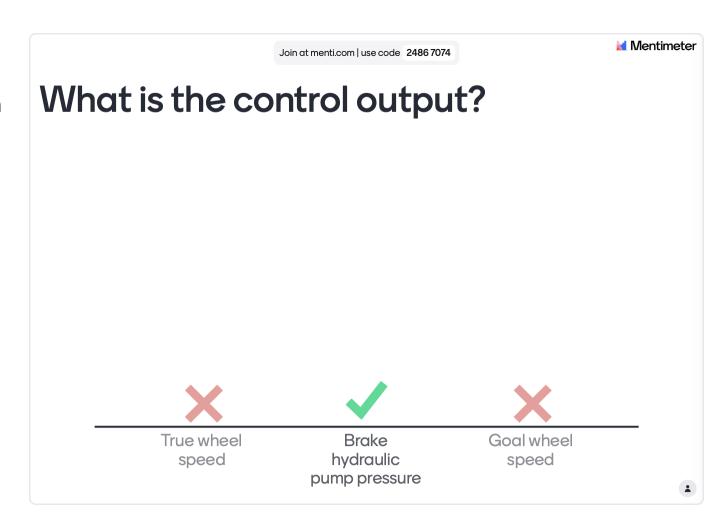
- Anti-Lock Braking System (ABS) in vehicles
 - Prevent lock-up during braking
 - Maintain high braking power and traction

Controllable Objects

Brake hydraulic pump

Information

- Wheel speed
- Brake hydraulic pump pressure







Goal

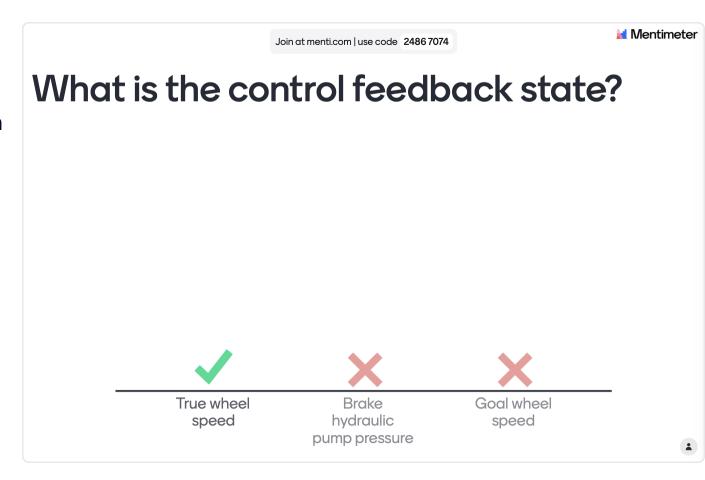
- Anti-Lock Braking System (ABS) in vehicles
 - Prevent lock-up during braking
 - Maintain high braking power and traction

Controllable Objects

Brake hydraulic pump

Information

- Wheel speed
- Brake hydraulic pump pressure







Next Week

- By next Wednesday:
 - Group up (5-6 ppl/group)
 - Register on Moodle;
 - 3 project ideas
 - Prepare a 3 min presentation for the ideas